Bounds on steady states for a non-systemically autocatalysed reaction-diffusion system

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## LETTER TO THE EDITOR

# Bounds on steady states for a non-systemically autocatalysed reaction-diffusion system 

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Received 7 February 1990


#### Abstract

Bounds on parameter values that lead to different types of solutions for a non-systemically autocatalysed reaction-diffusion system are derived and show the existence of a critical concentration beyond which the stability properties undergo change. Additionally, bifurcating solutions at the zero eigenvalue are obtained.


This letter considers an alternative form of autocatalysis where the product formed affects its own rate through interactions with the rate constant as against the normal autocatalysis where the rate is affected directly by the concentration of the product. This form of the rate has wide applications in several biochemical systems as well as in explaining the phenomena in diverse chemical and combustion-type reactions (Ravi Kumar et al 1984). The exponential autocatalysis has received acceptance as a general model for a class of reaction-diffusion systems (Bar-Eli 1984a, b, c, 1985) and results obtained by using the conventional autocatalysis, such as the one used in Brusselatortype models, compare well with this model system. The exponential autocatalysis has revealed the existence of multiplicity and oscillatory behaviour under homogeneous conditions (Ravi Kumar et al 1984). This letter begins with this reaction scheme to derive bounds on the values of the parameters that lead to the existence of different types of solutions in presence of diffusion gradients.

More specifically the conditions under which the governing system would have real eigenvalues with positive real part, the conditions when eigenvalues are complex and the conditions when the complex eigenvalues have real positive parts have been derived. In addition to this, bifucating solutions for a simple case of zero eigenvalue are obtained. The mathematical aspects of reacting and diffusing systems are well documented (see, for example, Sattinger 1973, Auchmuty and Nicolis 1975a, b, Fife 1979, Kuramoto 1984), but the present scheme provides an example where the functions involved are transcendental in nature.

The reaction-diffusion system is represented by following coupled nonlinear parabolic partial differential equations:

$$
\begin{align*}
& \frac{\partial x}{\partial t}=D_{1} \frac{\partial^{2} x}{\partial r^{2}}+x_{0}-x-D a_{1} x \exp (\alpha y) \\
& \frac{\partial y}{\partial t}=D_{2} \frac{\partial^{2} y}{\partial r^{2}}+y_{0}-y+D a_{1} x \exp (\alpha y)-D a_{2} y . \tag{1}
\end{align*}
$$

[^0]At steady state, the values of $x$ and $y$, denoted as $x_{\mathrm{s}}$ and $\theta$ respectively, are given by

$$
\begin{equation*}
\exp (\alpha \theta)=\frac{\left(x_{0}-x_{\mathrm{s}}\right)}{x_{\mathrm{s}} D a_{1}} \quad \theta=\frac{x_{0}+y_{0}-x_{\mathrm{s}}}{1+D a_{2}} . \tag{2}
\end{equation*}
$$

Defining deviations from steady state as $u$ and $v$

$$
\begin{equation*}
x=u+x_{\mathrm{s}} \quad y=v+\theta \tag{3}
\end{equation*}
$$

and with linearisation of the nonlinear term $\exp (\alpha v)=(1+\alpha v)$, equation (1) can be rewritten as

$$
\begin{align*}
& \frac{\partial u}{\partial t}=D_{1} \frac{\partial^{2} u}{\partial r^{2}}-\left(1+D a_{1} \mathrm{e}^{\alpha \theta}\right) u-\left(\alpha D a_{1} x_{\mathrm{s}} \mathrm{e}^{\alpha \theta} v\right)-\alpha D a_{1} \mathrm{e}^{\alpha \theta} u v  \tag{4a}\\
& \frac{\partial v}{\partial t}=D_{2} \frac{\partial^{2} v}{\partial r^{2}}+D a_{1} \mathrm{e}^{\alpha \theta} u+\left(\alpha D a_{1} x_{\mathrm{s}} \mathrm{e}^{\alpha \theta}-\left(1+D a_{2}\right)\right) v+\alpha D a_{1} \mathrm{e}^{\alpha \theta} u v \tag{4b}
\end{align*}
$$

The eigenvalue problem for equations (4a) and (4b) can be formulated as:

$$
\begin{align*}
& D_{1} u^{\prime \prime}-\left(1+D a_{1} \mathrm{e}^{\alpha \theta}\right) u-\alpha D a_{1} x_{\mathrm{s}} \mathrm{e}^{\alpha \theta} v=\lambda u  \tag{5a}\\
& D_{2} v^{\prime \prime}+D a_{1} \mathrm{e}^{\alpha \theta} u+\left(\alpha D a_{1} x_{\mathrm{s}} \mathrm{e}^{\alpha \theta}-\left(1+D a_{2}\right)\right) v=\lambda v . \tag{5b}
\end{align*}
$$

Using equations ( $5 a$ ) and ( $5 b$ ), and defining constants $k_{1}, k_{2}, k_{3}, k_{4}$ for the sake of simplification as,

$$
\begin{align*}
& k_{1}=-\left(1+D a_{1} \mathrm{e}^{\alpha \theta}\right) \quad k_{2}=-\alpha D a_{1} x_{\mathrm{s}} \mathrm{e}^{\alpha \theta}  \tag{6}\\
& k_{3}=\alpha x_{\mathrm{s}} D a_{1} \mathrm{e}^{\alpha \theta}-\left(1+D a_{2}\right) \quad k_{4}=D a_{1} \mathrm{e}^{\alpha \theta} \tag{7}
\end{align*}
$$

the solution to the eigenvalue problem can be given as

$$
\begin{equation*}
\binom{u_{m}(r)}{v_{m}(r)}=\binom{c_{1}}{c_{2}} \sin m \pi r . \tag{8}
\end{equation*}
$$

From equations (5)-(8) we obtain

$$
\begin{align*}
& c_{1}^{2}+c_{2}^{2}=2  \tag{9}\\
& \delta_{m}=\frac{c_{2}}{c_{1}}=\frac{-m^{2} \pi^{2} D_{1}+k_{1}}{k_{2}} \tag{10}
\end{align*}
$$

giving us $c_{1}$ and $c_{2}$ as

$$
\begin{equation*}
c_{1}=\frac{\sqrt{2}}{\sqrt{1+\delta_{m}^{2}}} \quad c_{2}=\frac{\sqrt{2} \delta_{m}}{\sqrt{1+\delta_{m}^{2}}} \tag{11}
\end{equation*}
$$

The system of linear equations possesses the following characteristic equation:

$$
\begin{equation*}
\lambda^{2}+\left(\beta_{m}-\alpha_{m}\right) \lambda+\alpha x_{\mathrm{s}}\left(D a_{1} \mathrm{e}^{\alpha \theta}\right)^{2}-\alpha_{m} \beta_{m}=0 \tag{12}
\end{equation*}
$$

The eigenvalues are the roots of the characteristic equation given by

$$
\begin{equation*}
\lambda^{ \pm}=\frac{1}{2}\left\{\left(\alpha_{m}-\beta_{m}\right) \pm\left[\left(\alpha_{m}+\beta_{m}\right)^{2}-4 \alpha x_{\mathrm{s}}\left(D a_{1} \mathrm{e}^{\alpha \theta}\right)^{2}\right]^{1 / 2}\right\} \tag{13}
\end{equation*}
$$

Analysis of equation (13) helps us to fix the following conditions for different stability behaviour of steady state solutions.
(1) $\lambda^{+}$has positive real part whenever

$$
\begin{equation*}
y_{0}>\left(x_{\mathrm{s}}-x_{0}\right)+\frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{\frac{m^{4} \pi^{4} D_{1} D_{2}+m^{2} \pi^{2}\left[D_{1}\left(1+D a_{2}\right)+D_{2}\right]+\left(1+D a_{2}\right)}{D a_{1}\left[m^{2} \pi^{2}\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)+\left(\alpha x_{\mathrm{s}}-D a_{2}-1\right)\right]}\right\} . \tag{14}
\end{equation*}
$$

(2) The eigenvalues are complex whenever the discriminant in equation (12) obeys the condition $\Delta<0$. The resulting inequality is

$$
\begin{align*}
&\left(x_{\mathrm{s}}-x_{0}\right)+\frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{\frac{\left(\alpha x_{\mathrm{s}}+1\right)\left(1+D a_{2}-\delta\right)-\psi}{D a_{1}\left(\alpha x_{\mathrm{s}}-1\right)^{2}}\right\}<y_{0} \\
&<\left(x_{\mathrm{s}}-x_{0}\right)+\frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{\frac{\left(\alpha x_{\mathrm{s}}+1\right)\left(1+D a_{2}-\delta\right)+\psi}{D a_{1}\left(\alpha x_{\mathrm{s}}-1\right)^{2}}\right\} \tag{15}
\end{align*}
$$

where

$$
\begin{equation*}
\psi=\left\{4\left[\alpha x_{\mathrm{s}}(\delta-1)^{2}-D a_{2}(\delta-1)\left(\alpha^{2} x_{\mathrm{s}}^{2}+1\right)+\alpha x_{\mathrm{s}} D a_{2}^{2}\right]+\left(\alpha x_{\mathrm{s}}-1\right)^{2}\right\}^{1 / 2} \tag{16}
\end{equation*}
$$

and

$$
\begin{equation*}
\delta=1+m^{2} \pi^{2}\left(D_{1}-D_{2}\right) \tag{17}
\end{equation*}
$$

(3) A complex value will have positive real part provided

$$
\begin{equation*}
y_{0}>\left(x_{\mathrm{s}}-x_{0}\right)+\frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{\frac{\delta^{\prime}+D a_{2}+1}{D a_{1}\left(\alpha x_{\mathrm{s}}-1\right)}\right\} \tag{18}
\end{equation*}
$$

where

$$
\begin{equation*}
\delta^{\prime}=1+m^{2} \pi^{2}\left(D_{1}+D_{2}\right) \tag{19}
\end{equation*}
$$

Combining the two inequalities given by equations (15) and (18), one sees that

$$
\begin{align*}
\left(x_{\mathrm{s}}-x_{0}\right)+ & \frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{\frac{\delta^{\prime}+D a_{2}+1}{D a_{1}\left(\alpha x_{\mathrm{s}}-1\right)}\right\} \\
& <y_{0}<\left(x_{\mathrm{s}}-x_{0}\right)+\frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{\frac{\left(\alpha x_{\mathrm{s}}+1\right)\left(1+D a_{2}-\delta\right)-\psi}{D a_{1}\left(\alpha x_{\mathrm{s}}-1\right)^{2}}\right\} . \tag{20}
\end{align*}
$$

The equations (15) and (16) can be rewritten as:

$$
\begin{align*}
m^{4} \pi^{4}\left(D_{1}-D_{2}\right)^{2} & +2 m^{2} \pi^{2}\left\{\left(D_{1}-D_{2}\right)\left[D a_{1} \mathrm{e}^{\alpha \theta}\left(\alpha x_{\mathrm{s}}+1\right)-D a_{2}\right]\right\} \\
& +\left\{\left(\alpha x_{\mathrm{s}}-1\right)^{2}\left(D a_{1} \mathrm{e}^{\alpha \theta}\right)^{2}-2 D a_{2}\left(\alpha x_{\mathrm{s}}+1\right) D a_{1} \mathrm{e}^{\alpha \theta}+D a_{2}^{2}-1\right\}=0 . \tag{21}
\end{align*}
$$

Now, to obtain the critical value of the wavenumber $m_{c}$ or $\mu$ we shall minimise the function in equation (14). If $f=m^{2} \pi^{2}$, then we have the following quadratic equation:

$$
\begin{align*}
& f^{2}\left\{D_{1} D_{2}\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)\right\}+f\left\{2 D_{1} D_{2}\left(\alpha x_{\mathrm{s}}-D a_{2}-1\right)\right\} \\
& \quad+\left(\alpha x_{\mathrm{s}}-D a_{2}-1\right)\left[\left(1+D a_{2}\right) D_{1}+D_{2}\right]-\left(1+D a_{2}\right)\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)=0 \tag{22}
\end{align*}
$$

giving

$$
\begin{equation*}
f=\frac{\left(1+D a_{2}-\alpha x_{\mathrm{s}}\right) D_{1} D_{2} \pm q}{D_{1} D_{2}\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)} \tag{23a}
\end{equation*}
$$

where

$$
\begin{align*}
& q=\llbracket\left[D_{1} D_{2}\left(\alpha x_{\mathrm{s}}-D a_{2}-1\right)\right]^{2}-\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right) \\
& \times\left\{D_{1} D_{2}\left(\alpha x_{\mathrm{s}}-D a_{2}-1\right)\left[\left(1+D a_{2}\right) D_{1}+D_{2}\right]+\frac{1}{4}\left(1+D a_{2}\right)\right\} \rrbracket^{1 / 2} \tag{23b}
\end{align*}
$$

From equations (14), (22) and (23), we obtain the expression for critical value of bifurcating parameter as:

$$
\begin{align*}
y_{o_{\mathrm{c}}} \geqslant\left(x_{\mathrm{s}}-x_{0}\right)+ & \frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{ \pm \frac{D_{1} D_{2}}{q}\left[2\left(1+D a_{2}\right)-\frac{\left(\alpha x_{\mathrm{s}}-D a_{2}-1\right)\left[\left(1+D a_{2}\right) D_{1}+D_{2}\right]}{\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)}\right.\right. \\
& \left.\left.+\frac{\left(1+D a_{2}-\alpha x_{\mathrm{s}}\right) D_{1} D_{2} \pm q}{\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)}\left(\frac{2\left(1+D a_{2}-\alpha x_{\mathrm{s}}\right)}{\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)}+\frac{D_{1}\left(1+D a_{2}\right)+D_{2}}{D_{1} D_{2}}\right)\right]\right\} . \tag{24}
\end{align*}
$$

From equation (18), one gets

$$
\begin{equation*}
y_{01}=\left(x_{\mathrm{s}}-x_{0}\right)+\frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{\frac{1+\pi^{2}\left(D_{1}+D_{2}\right)+\left(1+D a_{2}\right)}{\left(\alpha x_{\mathrm{s}}-1\right) D a_{1}}\right\} . \tag{25}
\end{equation*}
$$

Then combining inequalities (20) and (25),

$$
D_{2}<2\left(D a_{2}+2+\pi^{2} D_{1}\right)
$$

$$
\begin{equation*}
-\left\{4\left[\alpha x_{\mathrm{s}}\left(\delta_{0}-1\right)^{2}-D a_{2}\left(\delta_{0}-1\right)\left(\alpha^{2} x_{\mathrm{s}}^{2}+1\right)+\alpha x_{\mathrm{s}} D a_{2}^{2}\right]+\left(\alpha x_{\mathrm{s}}-1\right)^{2}\right\}^{1 / 2} \tag{26}
\end{equation*}
$$

where

$$
\begin{equation*}
\delta_{0}=1+\pi^{2}\left(D_{1}-D_{2}\right) . \tag{27}
\end{equation*}
$$

In particular, if $D_{1}=D_{2}=D$, equation (26) becomes

$$
\begin{equation*}
D<\frac{2\left(D a_{2}+2\right)-\left[4 \alpha x_{\mathrm{s}} D a_{2}^{2}+\left(\alpha x_{\mathrm{s}}-1\right)^{2}\right]^{1 / 2}}{1-2 \pi^{2}} . \tag{28}
\end{equation*}
$$

For a simple zero eigenvalue, the eigenfunction has a condition for the wavenumber as

$$
\alpha_{m} \beta_{m}=\alpha x_{\mathrm{s}}\left(D a_{1} \mathrm{e}^{\alpha \theta}\right)^{2}
$$

This produces the following quadratic equation:

$$
\begin{array}{r}
m^{4} D_{1} D_{2}+\frac{m^{2}}{\pi^{2}}\left\{D_{1}\left[\alpha x_{\mathrm{s}} D a_{1} \mathrm{e}^{\alpha \theta}-\left(1+D a_{2}\right)\right]-D_{2}\left(1+D a_{1} \mathrm{e}^{\sigma \theta}\right)\right\} \\
+  \tag{29}\\
+\frac{1}{\pi^{4}}\left\{\alpha x_{\mathrm{s}} D a_{1} \mathrm{e}^{\alpha \theta}-\left(1+D a_{2}\right)\left(1+D a_{1} \mathrm{e}^{\alpha \theta}\right)\right\}=0
\end{array}
$$

or for $y_{0 m}$ we can rewrite equation (29) using the critical value of $m$ as

$$
\begin{align*}
y_{0 m} \geqslant\left(x_{\mathrm{s}}-x_{0}\right) & +\frac{\left(1+D a_{2}\right)}{\alpha} \ln \left\{ \pm \frac{D_{1} D_{2}}{q}\left[2\left(1+D a_{2}\right)-\frac{\left(\alpha x_{\mathrm{s}}-D a_{2}-1\right)\left[\left(1+D a_{2}\right) D_{1}+D_{2}\right]}{\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)}\right.\right. \\
& \left.\left.+\frac{\left(1+D a_{2}-\alpha x_{\mathrm{s}}\right) D_{1} D_{2} \pm q}{\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)}\left(\frac{2\left(1+D a_{2}-\alpha x_{\mathrm{s}}\right)}{\left(\alpha x_{\mathrm{s}} D_{1}-D_{2}\right)}+\frac{D_{1}\left(1+D a_{2}\right)+D_{2}}{D_{1} D_{2}}\right)\right]\right\} . \tag{30}
\end{align*}
$$

In a similar fashion, we can substitute the value of $m_{c}$ into equation (30), and obtain another relationship, which confirms that $y_{0}=0$ can never be a bifurcation point.

Now for the quadratic equation (29) in $m^{2}$, there exist two positive integers $m_{1}$ and $m_{2}$ such that,

$$
D_{1} D_{2}\left(m^{2}-m_{1}^{2}\right)\left(m^{2}-m_{2}^{2}\right)=0
$$

When $m_{1}$ is an integer solution, this yields a condition,

$$
\begin{equation*}
\nu=\frac{\left(1+D a_{2}\right)-\alpha x_{\mathrm{s}} D a_{1} \mathrm{e}^{\alpha \theta}}{D_{2}}+\frac{1+D a_{1} \mathrm{e}^{\alpha \theta}}{D_{1}}-m_{1}^{2} \tag{31}
\end{equation*}
$$

which is not a square.
For the normalised eigenvector given in equation (8), using equations (9)-(11), the constants $c_{1}$ and $c_{2}$ can be computed. Similarly, putting the critical value of wavenumber $m_{\mathrm{c}}$, we can see that

$$
\begin{equation*}
c_{2} / c_{1}<0 \tag{32}
\end{equation*}
$$

The adjoint $L_{y_{0}}^{*}$ of $L_{y_{0}}$ is given as

$$
L_{y_{0}}^{*}\binom{u}{v}=\left(\begin{array}{cc}
D_{1} \nabla_{r}+k_{1} & k_{4}  \tag{33}\\
k_{2} & D_{2} \nabla_{r}+k_{3}
\end{array}\right)\binom{u}{v}
$$

with the condition

$$
\begin{equation*}
u=v=0 \tag{34}
\end{equation*}
$$

The eigenvalues of the adjoint operator $L_{y_{0}}^{*}$ are the same as that of $L_{y_{0}}$, and the eigenfunction for simple zero eigenvalue is given as

$$
\begin{equation*}
\binom{u_{m}(r)}{v_{m}(r)}=\binom{d_{1}}{d_{2}} \sin m \pi r . \tag{35}
\end{equation*}
$$

Using equations (5) and (35) we obtain

$$
\begin{align*}
& d_{1}^{2}+d_{2}^{2}=2  \tag{36}\\
& \varepsilon_{m}=\frac{d_{1}}{d_{2}}=\frac{-m^{2} \pi^{2} D_{2}+k_{3}}{k_{2}} \tag{37}
\end{align*}
$$

which produces expressions for $d_{1}$ and $d_{2}$ as

$$
\begin{equation*}
d_{1}=\frac{\sqrt{2} \varepsilon_{m}}{\sqrt{1+\varepsilon_{m}^{2}}} \quad d_{2}=\frac{\sqrt{2}}{\sqrt{1+\varepsilon_{m}^{2}}} \tag{38}
\end{equation*}
$$

This letter presents the analysis of the steady state solutions of the system of nonlinear equations which describe an exponentially autocatalysed reaction with diffusion. The stability of steady state solutions of the system has been derived using a linear stability analysis. In particular, criteria in terms of the bounds on the values of a parameter appearing in the equations are developed. The analysis reveals the existence of the critical value $y_{0 c}$ of a component $y$ beyond which the uniform steady state solutions undergo a change in stability properties. It is possible to have additional steady state solutions of the system of equations, which may be stable for the various ranges of $y_{0}$. These solutions, however, are inhomogeneous and possess several well defined maxima or minima. The results here form a basis for obtaining the so-called dissipative structures.

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[^0]:    $\dagger$ NCL Communication Number: 4833.

